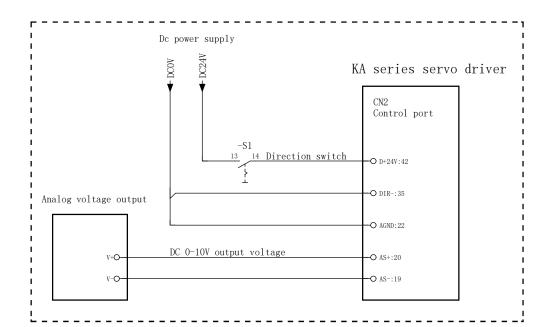
## Speed control mode



## Parameter Settings:

No	Name	Setting value
P00. 04	Control Strategy choice	6
P02.00	Analog speed command gain	According to the need to set
P02. 01	Analog speed instruction The input direction is reversed	0 or 1

## Zero drift adjustment method:

If the analog voltage output is OV, the motor will rotate slightly. First set the parameter PO3.04 to 1, and then press Enter to confirm, the driver automatically adjusts zero drift, and the motor almost does not turn.

Then adjust PO2.03 to increase the non-acting area of the setting voltage, and finally observe the current speed of the motor. If it is 0 revolution, the debugging is successful.

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设计	日期	审核	项目名称
	2022/1/11		伺服驱动器接线示意图



